

# 34 Line impedance, generalized reflection coefficient, Smith Chart

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- Consider a TL of an arbitrary length  $l$  terminated by an arbitrary load

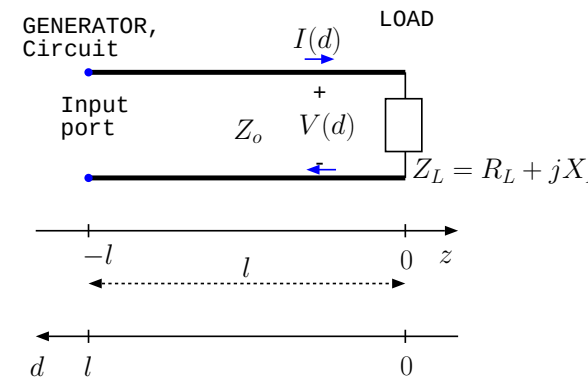
$$Z_L = R_L + jX_L.$$

as depicted in the margin.

Voltage and current phasors are known to vary on the line as

$$V(d) = V^+ e^{j\beta d} + V^- e^{-j\beta d} \quad \text{and} \quad I(d) = \frac{V^+ e^{j\beta d} - V^- e^{-j\beta d}}{Z_o}.$$

In this lecture we will develop the general analysis tools needed to determine the unknowns of these phasors, namely  $V^+$  and  $V^-$ , in terms of source circuit specifications.



- Our analysis starts at the load end of the TL where  $V(0)$  and  $I(0)$  stand for the load voltage and current, obeying Ohm's law

$$V(0) = Z_L I(0).$$

Hence, using  $V(0)$  and  $I(0)$  from above, we have

$$V^+ + V^- = Z_L \frac{V^+ - V^-}{Z_o} \Rightarrow V^- = \frac{Z_L - Z_o}{Z_L + Z_o} V^+.$$

- Define a **load reflection coefficient**

$$\Gamma_L \equiv \frac{Z_L - Z_o}{Z_L + Z_o}$$

and re-write the voltage and current phasors as

$$V(d) = V^+ e^{j\beta d} [1 + \Gamma_L e^{-j2\beta d}] \quad \text{and} \quad I(d) = \frac{V^+ e^{j\beta d} [1 - \Gamma_L e^{-j2\beta d}]}{Z_o}.$$

- Define a **generalized reflection coefficient**

$$\Gamma(d) \equiv \Gamma_L e^{-j2\beta d}$$

and re-write the voltage and current phasors as

$$V(d) = V^+ e^{j\beta d} [1 + \Gamma(d)] \quad \text{and} \quad I(d) = \frac{V^+ e^{j\beta d} [1 - \Gamma(d)]}{Z_o}.$$

- **Line impedance** is then defined as

$$Z(d) = \frac{V(d)}{I(d)} = Z_o \frac{1 + \Gamma(d)}{1 - \Gamma(d)}$$

for all values of  $d$  on the line extending from the load point  $d = 0$  all the way to the input port at  $d = l$ .

With the dependence on  $d$  of  $Z(d)$  as well as  $\Gamma(d)$  tacitly implied, we can re-write this important relation and its inverse as

$$\frac{Z}{Z_o} = \frac{1 + \Gamma}{1 - \Gamma} \quad \Leftrightarrow \quad \Gamma = \frac{Z - Z_o}{Z + Z_o}.$$

“Load reflection coefficient” is a well justified name for  $\Gamma_L$  since the forward traveling wave with phasor  $V^+ e^{j\beta d}$  gets reflected from the load.

The term “generalized reflection coefficient” is also well justified even if there is no reflection taking place at arbitrary  $d$  — the reason is, if the line were cut at location  $d$  and the stub with the load were replaced by a lumped load having a reflection coefficient equal to  $\Gamma(d)$ , then there would be no modification of the voltage and current variations on the line towards the generator.

Each location  $d$  on the line has an impedance  $Z$  and a reflection coefficient  $\Gamma$  linked by these equations.

**Properties of  $Z(d) = R(d) + jX(d)$  and  $\Gamma(d) = \Gamma_L e^{-j2\beta d}$  linked by the relations**

$$\frac{Z}{Z_o} = \frac{1 + \Gamma}{1 - \Gamma} \Leftrightarrow \Gamma = \frac{Z - Z_o}{Z + Z_o} :$$

1. **For real valued  $Z_o$  and  $R(d) \geq 0$  ,  $|\Gamma(d)| \leq 1$ :**

**Verification:**

$$|\Gamma| = \frac{|Z - Z_o|}{|Z + Z_o|} = \frac{|(R - Z_o) + jX|}{|(R + Z_o) + jX|} = \frac{\sqrt{(R - Z_o)^2 + X^2}}{\sqrt{(R + Z_o)^2 + X^2}}.$$

Since with  $R \geq 0$

$$\sqrt{(R - Z_o)^2 + X^2} \leq \sqrt{(R + Z_o)^2 + X^2} \Rightarrow |\Gamma| \leq 1.$$

2. Since

$$|\Gamma| = |\Gamma_L| \quad \text{and} \quad \angle \Gamma(d) = \angle \Gamma_L - 2\beta d$$

property (1) implies that  $\Gamma(d)$  is a complex number which is constrained to be **on or within the unit-circle on the complex plane**.

3. Relationships

$$\frac{Z}{Z_o} = \frac{1 + \Gamma}{1 - \Gamma} \Leftrightarrow \Gamma = \frac{Z - Z_o}{Z + Z_o}$$

between  $\Gamma$  and  $Z$  are known as **bilinear transformations** — here the term *bilinear* refers to the numerator *as well as* the denominator of these transformations being *linear* in the variable being transformed (from right to left).

Bilinear (or Möbius) transformations are known to have the general property of mapping **straight lines** into **circles** on the complex number plane.

- Bilinear transformations between

$$\Gamma \equiv \Gamma_r + j\Gamma_i \equiv (\Gamma_r, \Gamma_i)$$

and

$$\frac{Z}{Z_o} \equiv z \equiv r + jx,$$

known as **normalized impedance**, lead to an ingenious graphical aid known as the **Smith Chart**.

- On a Smith Chart (SC), straight lines on the right hand side of the complex number plane (see margin), represented by

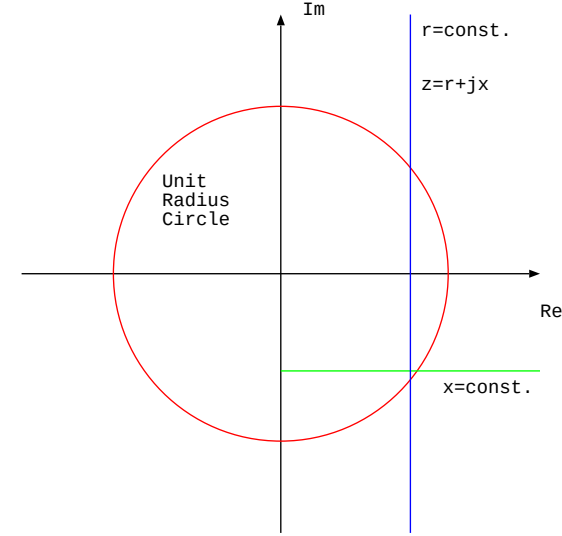
$$r = \text{const.} \quad \text{and} \quad x = \text{const.},$$

are mapped onto circular loci of

$$(\Gamma_r, \Gamma_i) = \Gamma = \frac{Z - Z_o}{Z + Z_o} = \frac{z - 1}{z + 1}$$

occupying the region of the plane bordered by the unit circle.

Circles corresponding to  $z = \text{const.} + jx$  and  $z = r + j\text{const.}$  constitute a **gridding** of the unit circle and its interior. By means of this **grid**, the normalized impedance  $z$  corresponding to every possible  $\Gamma$  can be directly read off the SC.



- SC can be constructed by first noting that

$$\Gamma = \frac{z - 1}{z + 1} = \frac{r + jx - 1}{r + jx + 1} = \frac{[(r - 1) + jx][(r + 1) - jx]}{(r + 1)^2 + x^2} = \frac{(r^2 + x^2 - 1) + j2x}{(r + 1)^2 + x^2} \equiv \Gamma_r + j\Gamma_i;$$

thus

$$\Gamma_r = \frac{(r^2 + x^2 - 1)}{(r + 1)^2 + x^2} \text{ and } \Gamma_i = \frac{2x}{(r + 1)^2 + x^2},$$

and by direct substitution we can verify the following equations

$$\left(\Gamma_r - \frac{r}{r + 1}\right)^2 + \Gamma_i^2 = \left(\frac{1}{r + 1}\right)^2 \text{ and } (\Gamma_r - 1)^2 + \left(\Gamma_i - \frac{1}{x}\right)^2 = \left(\frac{1}{x}\right)^2$$

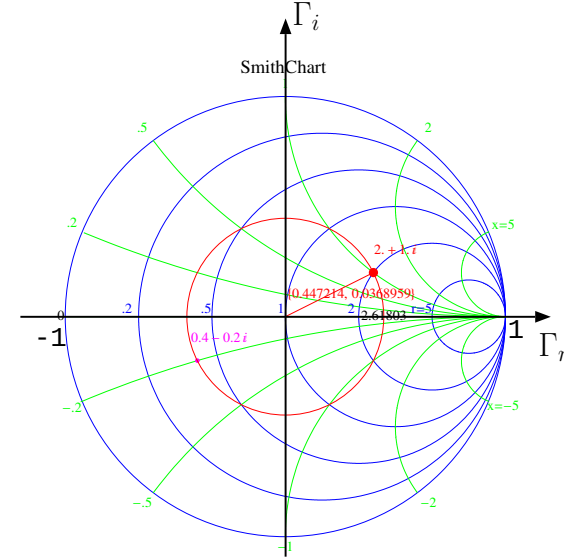
describing  $r$  and  $x$  dependent circles, respectively, on complex plane constituting the grid lines of the SC.

- Typical SC usage:

1. Locate and mark  $z(0)$  — normalized load impedance — on the SC, which places you at a distance  $|\Gamma(0)| = |\Gamma_L|$  from the origin of the complex plane (and the SC), at an angle of  $\theta = \angle\Gamma(0)$ .
2. Draw a constant  $|\Gamma| = |\Gamma_L|$  circle with a compass going through point  $z(0)$  on the SC (the read circle in the margin). Rotate clockwise on the circle by an angle of

$$2\beta d = \frac{4\pi}{\lambda}d \text{ rad} = \frac{d}{\lambda/2} 360^\circ$$

to land on  $z(d)$  that can be read off using the SC gridding.



*Smith Chart* is the unit circle and its interior on the complex number plane corresponding to the *generalized reflection coefficient*  $\Gamma$ . The gridding allows direct identification of the bilinear transform of  $\Gamma$ , namely the *normalized line impedance*  $z$ .

- Rotation by an angle of  $2\beta d$  amounts to rotation by full circle for  $d = \frac{\lambda}{2}$ ,  
rotation by half circle for  $d = \frac{\lambda}{4}$ ,  
rotation by quarter circle for  $d = \frac{\lambda}{8}$ , etc.

3. Also,

$$y(d) \equiv \frac{1}{z(d)}$$

which is the **normalized line admittance** is located on the SC on the constant  $|\Gamma| = |\Gamma_L|$  circle across the point corresponding to  $z(d)$ .

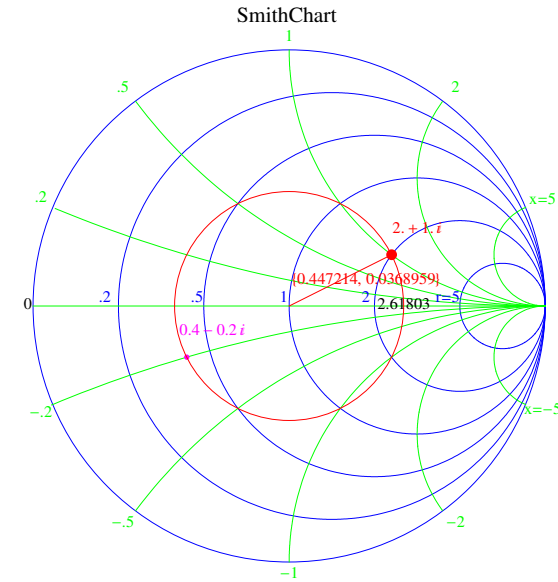
**Verification:** Since

$$z = \frac{1 + \Gamma}{1 - \Gamma} \Rightarrow y = \frac{1}{z} = \frac{1 - \Gamma}{1 + \Gamma} = \frac{1 + (-\Gamma)}{1 - (-\Gamma)};$$

hence whereas  $z$  is the transform of  $\Gamma$ ,  $y$  is the transform of  $-\Gamma$ , having the same magnitude as  $\Gamma$  but an angle off by  $\pm 180^\circ$ .

- Therefore, **“reflect” on the SC across the origin** to jump from  $z(d)$  to  $y(d)$  if you need the value of the normalized admittance.

Our first SC example is given next.



**Example 1:** A transmission line is terminated by an inductive load of

$$Z_L = 50 + j100 \Omega.$$

Determine the input impedance  $Z_{in} = Z(l)$  of the line at a distance

$$d = l = \frac{\lambda}{8}$$

if the characteristic impedance of the line is  $Z_o = 50 \Omega$ . Also determine the normalized input admittance  $y(l)$ .

**Solution:** The normalized load impedance is

$$z(0) = \frac{Z_L}{Z_o} = \frac{50 + j100}{50} = 1 + j2.$$

Enter  $z(0)$  on the SC and then rotate clockwise by  $\frac{\lambda}{8} \Leftrightarrow$  (quarter circle) to obtain the normalized input impedance

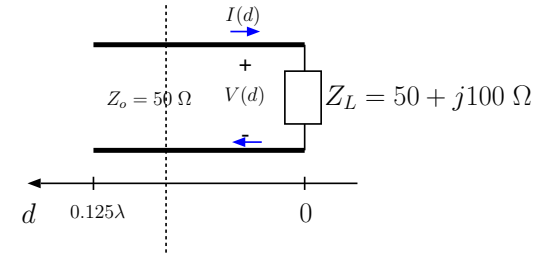
$$z(l) = 1 - j2,$$

and the normalized input admittance

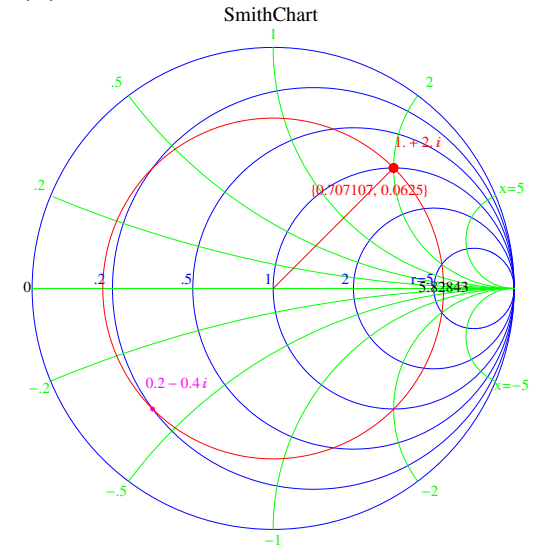
$$y(l) = 0.2 + j0.4$$

right across  $z(l)$ . The input impedance is

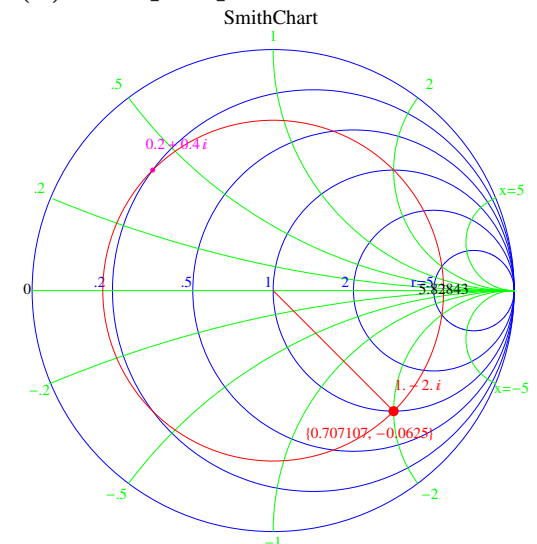
$$Z_{in} = Z_o z(l) = 50(1 - j2) = 50 - j100 \Omega.$$



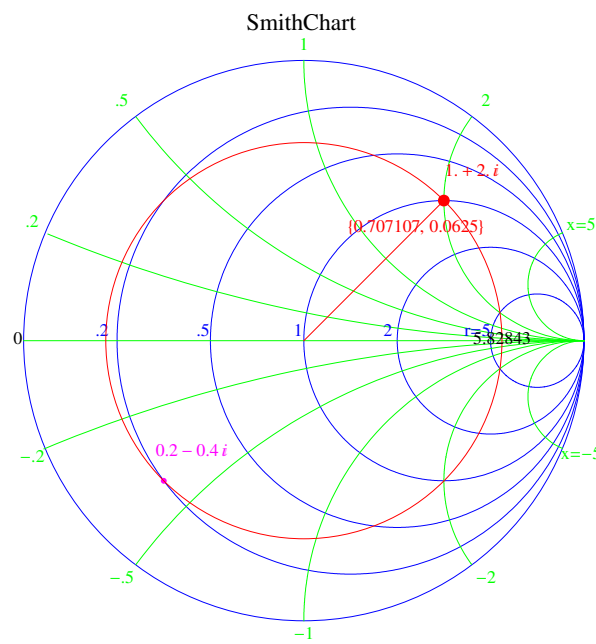
(a) At load point:



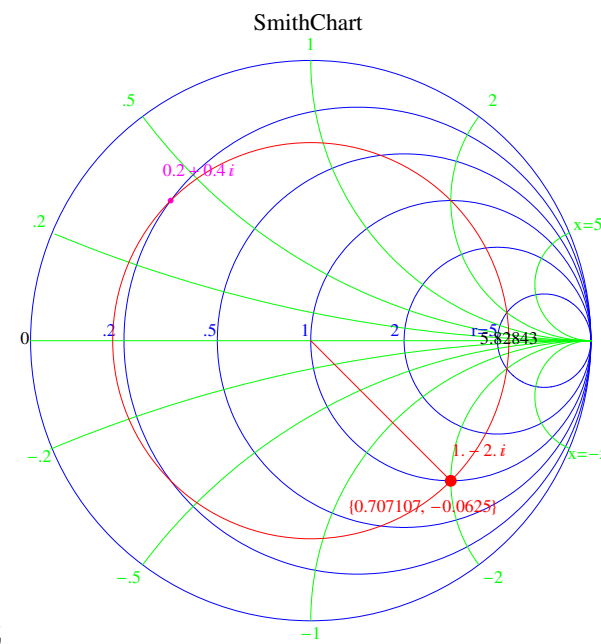
(b) at input point:



Blow up of the SC's used in Example 1:



(a) At load point



(b) at input point

- A SmithChartTool linked from the class calendar (a javascript utility that requires a Safari or Firefox browser to work properly) marks and prints  $z(d)$  in **red** and  $y(d)$  in **magenta** across from  $z(d)$  on the **constant- $|\Gamma_L|$  circle** (shown in red) as in the above examples. Also
  - printed in **black** is the real valued normalized impedance  $z(d_{max})$  discussed in the upcoming lectures (also known as VSWR).
  - also printed in **red** is  $|\Gamma_L| \angle \Gamma(d)$  where the second entry is expressed in terms of an equivalent  $\frac{d}{\lambda}$  such that  $\frac{d}{\lambda} = 0.5$  corresponds to an angle of  $360^\circ$ . This way of referring to  $\angle \Gamma(d)$  will be convenient in many SC applications that we will see.