

# 9 Static fields in dielectric media

- Summarizing important results from last lecture:
  - within a dielectric medium, displacement

$$\mathbf{D} = \epsilon \mathbf{E} = \epsilon_0 \mathbf{E} + \mathbf{P},$$

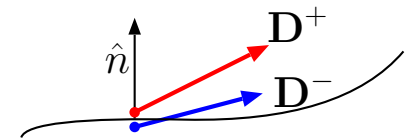
and if the permittivity  $\epsilon = \epsilon_r \epsilon_0$  is known,  $\mathbf{D}$  and  $\mathbf{E}$  can be calculated from free surface charge  $\rho_s$  or volume charge  $\rho$  in the region without resorting to  $\mathbf{P}$ .

- on surfaces separating perfect dielectrics,  $\hat{n} \cdot (\mathbf{D}^+ - \mathbf{D}^-) = 0$  typically, while  $\hat{n} \cdot \mathbf{D}^+ = \rho_s$  on a conductor-dielectric interface (with  $\hat{n}$  pointing from the conductor toward the dielectric).
- Gauss's law  $\nabla \cdot \mathbf{D} = \rho$  (and its integral counterpart) includes only the free charge density on its right side, which is typically zero in many practical problems.
- once  $\mathbf{D}$  and  $\mathbf{E}$  have been calculated (typically using the boundary condition equations), polarization  $\mathbf{P}$  can be obtained as

$$\mathbf{P} = \mathbf{D} - \epsilon_0 \mathbf{E}$$

if needed.

These rules will be used in the examples in this section.



**Example 1:** A perfect dielectric slab having a finite thickness  $W$  in the  $x$  direction is surrounded by free space and has a constant electric field  $\mathbf{E} = 18\hat{x}$  V/m in its exterior. Induced polarization of bound charges inside dielectric reduces the electric field strength inside the slab from  $18\hat{x}$  V/m to  $\mathbf{E} = 3\hat{x}$  V/m. What are the displacement field  $\mathbf{D}$  and polarization  $\mathbf{P}$  outside and inside the slab, and what are the dielectric constant  $\epsilon_r$  and electric susceptibility  $\chi_e$  of the slab?

**Solution:** Displacement field outside the slab, where  $\epsilon = \epsilon_o$ , must be

$$\mathbf{D} = \epsilon_o \mathbf{E} = \hat{x} 18 \epsilon_o \frac{\text{C}}{\text{m}^2}.$$

The outside polarization  $\mathbf{P}$  is of course zero. Boundary conditions at the interface of the slab with free space require the continuity of normal component of  $\mathbf{D}$  and tangential component of  $\mathbf{E}$  — both of these conditions would be satisfied if we were to take  $\mathbf{D} = \hat{x} 18 \epsilon_o \text{ C/m}^2$  also within the dielectric slab. Thus, with  $\mathbf{E} = 3\hat{x}$  V/m inside the slab, the condition  $\mathbf{D} = \epsilon_{slab} \mathbf{E}$  within the slab requires that

$$\epsilon_{slab} = 6\epsilon_o.$$

Consequently, the dielectric constant of the slab is

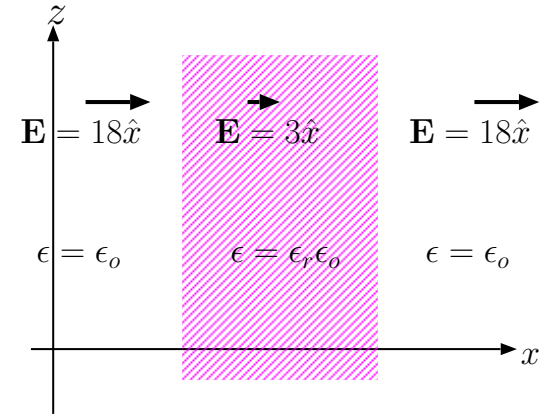
$$\epsilon_r = 1 + \chi_e = \frac{\epsilon_{slab}}{\epsilon_o} = 6$$

and its electric susceptibility is

$$\chi_e = \epsilon_r - 1 = 5.$$

Finally, since  $\mathbf{D} = \epsilon_o \mathbf{E} + \mathbf{P}$  in general, polarization  $\mathbf{P}$  inside the slab is

$$\mathbf{P} = \mathbf{D} - \epsilon_o \mathbf{E} = \hat{x} 18 \epsilon_o - \epsilon_o 3\hat{x} = \hat{x} 15 \epsilon_o \frac{\text{C}}{\text{m}^2}.$$



- Our revised definition of displacement  $\mathbf{D} = \epsilon \mathbf{E}$ , where  $\epsilon = \epsilon_r \epsilon_0$ , implies, when combined with  $\mathbf{E} = -\nabla V$  and  $\nabla \cdot \mathbf{D} = \rho$ , a revised form of Poisson's equation

$$\nabla^2 V = -\frac{\rho}{\epsilon},$$

- provided that dielectric constant  $\epsilon_r$  is independent of position so that  $\nabla \cdot \mathbf{D} = \nabla \cdot (\epsilon \mathbf{E}) = \epsilon \nabla \cdot \mathbf{E}$  is a valid intermediate step in the derivation of Poisson's equation.
- Under the same condition Laplace's equation  $\nabla^2 V = 0$  also remains valid.
- Dielectrics where  $\epsilon_r$  is independent of position are said to be **homogeneous**.
  - In **inhomogeneous** dielectrics where  $\epsilon$  varies with position neither equation is valid, and one has to resort to the full form of Gauss's law in field and potential calculations.

**In other words, don't use Laplace's/Poisson's equations in inhomogeneous media.**

In the next example we have two homogeneous slabs side-by-side making up an inhomogeneous configuration. In that case we can use Laplace/Poisson within the slabs one at a time and then match the results at the boundary using boundary condition equations as shown.

**Example 2:** A pair of infinite conducting plates at  $z = 0$  and  $z = 2$  m carry equal and opposite surface charge densities of  $-2\epsilon_0$  C/m<sup>2</sup> and  $2\epsilon_0$  C/m<sup>2</sup>, respectively. Determine  $V(2)$  if  $V(0) = 0$  and regions  $0 < z < 1$  m and  $1 < z < 2$  m are occupied by perfect dielectrics with permittivities of  $\epsilon_0$  and  $2\epsilon_0$ , respectively.

**Solution:** Given that  $V(0) = 0$ , we assume  $V(z) = Az$ , for some constant  $A$  in the homogeneous region  $0 < z < 1$  m, since  $V(z) = Az$  satisfies the Laplace's equation as well as the boundary condition at  $z = 0$ .

This gives  $V(1) = A$  at  $z = 1$  m, which then implies that we can take  $V(z) = A + B(z - 1)$  for the second homogeneous region  $1 < z < 2$  m having a different permittivity than the region below.

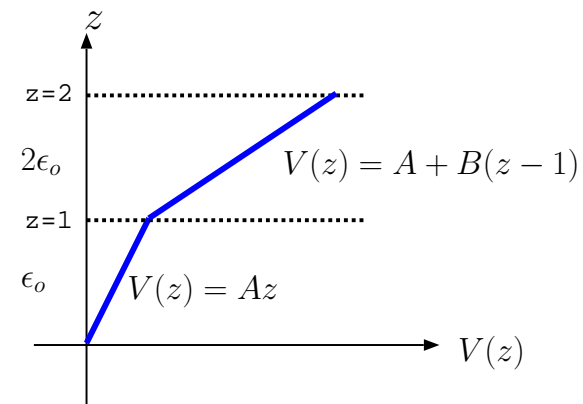
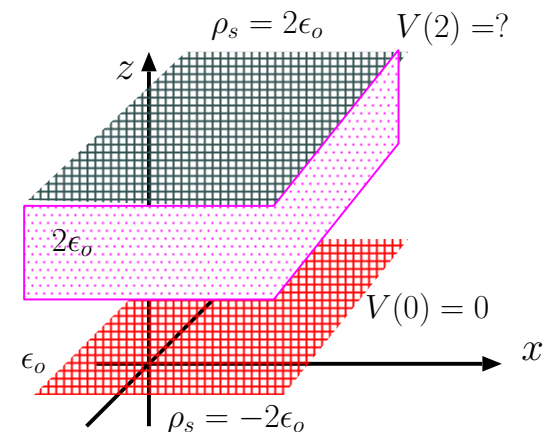
To determine the constants  $A$  and  $B$ , we will make use of boundary conditions at  $z = 0$  and  $z = 1$  m interfaces:

- In the region  $0 < z < 1$  m, the electric field  $\mathbf{E} = -\nabla(Az) = -A\hat{z}$ , and, therefore displacement  $\mathbf{D} = \epsilon_1\mathbf{E} = -\epsilon_0A\hat{z}$ . Hence, the pertinent boundary condition  $\hat{z} \cdot \mathbf{D}(0) = \rho_s$  yields

$$\hat{z} \cdot \mathbf{D}(0) = -\epsilon_0A = -2\epsilon_0 \Rightarrow A = 2.$$

- Just below  $z = 1$  m the displacement is  $\mathbf{D}(1^-) = -\epsilon_0A\hat{z} = -2\epsilon_0\hat{z}$  as we found out above. Above  $z = 1$  m, the electric field is  $\mathbf{E} = -\nabla(A + B(z - 1)) = -B\hat{z}$ , and, therefore,  $\mathbf{D}(1^+) = -2\epsilon_0B\hat{z}$  just above  $z = 1$  m. Hence, the pertinent boundary condition  $\hat{z} \cdot (\mathbf{D}(1^+) - \mathbf{D}(1^-)) = 0$  yields

$$\hat{z} \cdot (-2\epsilon_0B\hat{z} - (-2\epsilon_0\hat{z})) = -2\epsilon_0B + 2\epsilon_0 = 0 \Rightarrow B = 1.$$



Based on above calculations of constants  $A$  and  $B$ , the potential solution for the region is

$$V(z) = \begin{cases} 2zV, & 0 < z < 1 \\ 2 + (z - 1)V, & 1 < z < 2. \end{cases}$$

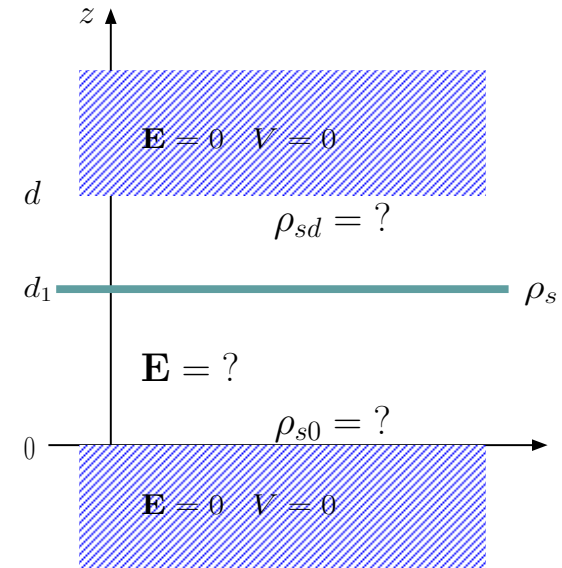
It follows that  $V(2) = 3V$ .

Note that electric fields  $-2\hat{z}V/m$  and  $-\hat{z}V/m$  in the bottom and top layers point from high to low potential regions. Electric field  $\mathbf{E}$  is discontinuous at the boundary at  $z = 1$  m while displacement  $\mathbf{D}$  is continuous — the continuity of normally directed  $\mathbf{D}$  is demanded by boundary condition equations in the absence of surface charge.

**Example 3:** A pair of infinite conducting plates at  $z = 0$  and  $z = d$  are grounded and have equal potentials, say,  $V = 0$ . The region  $0 < z < d$  is occupied by free space (i.e.,  $\epsilon = \epsilon_o$ ) except that an infinite charge sheet with a static surface charge density  $\rho_s$  is located at  $z = d_1 < d$ . Determine (a) the electrostatic field  $\mathbf{E}(z)$  in regions  $0 < z < d_1$  and  $d_1 < z < d$ , and (b) the surface charge densities  $\rho_{s0}$  and  $\rho_{sd}$  at  $z = 0$  and  $z = d$  on conductor surfaces if  $d_1 = d/2$ .

**Solution:** (a) Laplace's equation for the given geometry requires a linear (in  $z$ ) potential solution in regions  $0 < z < d_1$  and  $d_1 < z < d$ . Since electrostatic  $\mathbf{E} = -\nabla V$ , we can therefore represent the electric field in these regions as

$$\mathbf{E} = \begin{cases} -\hat{z}V_o/d_1, & 0 < z < d_1 \\ +\hat{z}V_o/d_2, & d_1 < z < d \end{cases}$$



If  $\rho_s$  in Example 3 is a slowly-varying function of time, then slowly varying  $\mathbf{E}$ ,  $\rho_{s0}$ , and  $\rho_{sd}$  calculated with instantaneous values of  $\rho_s$  would constitute *quasi-static solutions* which are valid so long as  $d \ll c/f$ , with  $f$  the highest frequency in  $\rho_s(t)$ .

where  $V_o \equiv V(d_1)$  and  $d_2 \equiv d - d_1$ . Hence,

$$\mathbf{D} = \epsilon_o \mathbf{E} = \begin{cases} -\hat{z} \epsilon_o V_o / d_1, & 0 < z < d_1 \\ +\hat{z} \epsilon_o V_o / d_2, & d_1 < z < d \end{cases},$$

and Maxwell's boundary condition equation applied on  $z = d_1$  surface is

$$\hat{z} \cdot (\mathbf{D}(d_1^+) - \mathbf{D}(d_1^-)) = \rho_s \Rightarrow \epsilon_o V_o \left( \frac{1}{d_2} + \frac{1}{d_1} \right) = \rho_s.$$

Thus

$$V_o = \frac{\rho_s}{\epsilon_o} \left( \frac{1}{d_2} + \frac{1}{d_1} \right)^{-1} = \frac{\rho_s}{\epsilon_o} \frac{d_1 d_2}{d_1 + d_2} = \frac{\rho_s}{\epsilon_o} \frac{d_1 d_2}{d}.$$

Substituting  $V_o$  back into the expression for  $\mathbf{E}$ , we have

$$\mathbf{E} = \begin{cases} -\hat{z} \frac{\rho_s}{\epsilon_o} \frac{d_2}{d}, & 0 < z < d_1 \\ +\hat{z} \frac{\rho_s}{\epsilon_o} \frac{d_1}{d}, & d_1 < z < d. \end{cases}$$

- (b) The surface charge at  $z = 0$  can be found by evaluating  $\hat{z} \cdot \mathbf{D} = \hat{z} \cdot \epsilon_o \mathbf{E}$  at  $z = 0$ . Hence,

$$\rho_{s0} = \hat{z} \cdot \epsilon_o \mathbf{E}(0) = -\frac{d_2}{d} \rho_s \overrightarrow{d_1 = d/2} - \frac{\rho_s}{2}.$$

Likewise,

$$\rho_{sd} = -\hat{z} \cdot \epsilon_o \mathbf{E}(d) = -\frac{d_1}{d} \rho_s \overrightarrow{d_1 = d/2} - \frac{\rho_s}{2}.$$

**Example 4:** Between a pair of infinite conducting plates at  $z = 0$  and  $z = 2$  m, the medium is a perfect dielectric with an **inhomogeneous** permittivity of

$$\epsilon(z) = \frac{4\epsilon_o}{4 - z}.$$

Determine the electric potential  $V(2)$  on the top plate if  $V(0) = 0$  and the surface charge density is  $\rho_s = 2\epsilon_o$  C/m<sup>2</sup> on the bottom plate at  $z = 0$ . Note that Laplace's equation cannot be used in this problem since the medium is inhomogeneous.

**Solution:** Consider Gauss's law

$$\nabla \cdot (\epsilon \mathbf{E}) = \rho$$

with  $\rho = 0$  in the region  $0 < z < 2$  m. Assuming that  $\mathbf{E} = \hat{z}E_z(z)$ , because the geometry is invariant in  $x$  and  $y$ , we have

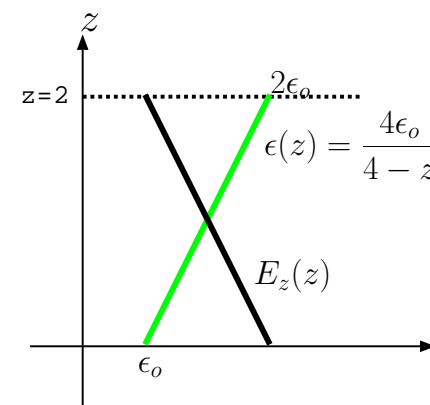
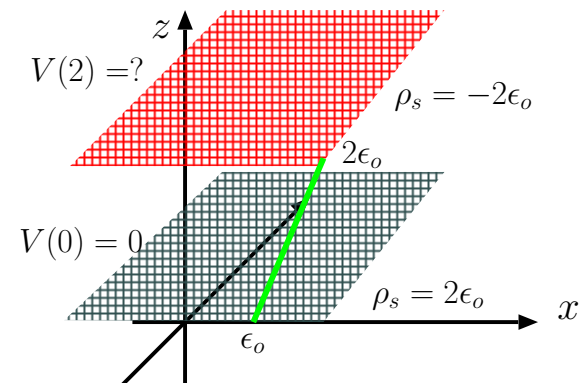
$$\nabla \cdot (\epsilon \mathbf{E}) = 0 \Rightarrow \frac{\partial}{\partial z}(\epsilon E_z) = 0 \Rightarrow \epsilon E_z = \text{constant}.$$

Thus the product  $\epsilon E_z$  is invariant with respect to coordinate  $z$ , which implies that

$$\epsilon(z)E_z(z) = \epsilon(0)E_z(0) \Rightarrow E_z(z) = \frac{\epsilon(0)}{\epsilon(z)}E_z(0) = E_z(0)\left(1 - \frac{z}{4}\right)$$

after substituting for  $\epsilon(z)$ . To identify  $E_z(0)$ , we apply the bottom boundary condition  $\hat{z} \cdot \mathbf{D}(0) = \rho_s$ , and obtain

$$D_z(0) = \epsilon(0)E_z(0) = 2\epsilon_o \Rightarrow E_z(0) = \frac{2\epsilon_o}{\epsilon(0)} = 2 \frac{V}{m}.$$



To determine  $V(2)$ , we integrate  $\mathbf{E} = \hat{z}2(1 - \frac{z}{4})$  V/m from top to bottom plate (grounded), obtaining

$$\begin{aligned} V(2) &= \int_{z=2}^0 \mathbf{E} \cdot d\mathbf{l} = \int_{z=2}^0 2(1 - \frac{z}{4}) dz \\ &= 2(z - \frac{z^2}{8}) \Big|_2^0 = -2(2 - \frac{4}{8}) = -2 \cdot \frac{3}{2} = -3 \text{ V}. \end{aligned}$$